

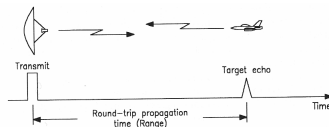
Radar Signal Processing

Ambiguity Function and Waveform Design
Golay Complementary Sequences (Golay Pairs)
Golay Pairs for Radar: Zero Doppler

Radar Problem

Transmit a waveform $s(t)$ and analyze the radar return $r(t)$:

$$r(t) = hs(t - \tau_o)e^{-j\omega(t - \tau_o)} + n(t)$$



h : target scattering coefficient; $\tau_o = 2d_o/c$: round-trip time;
 $\omega = 2\pi f_o \frac{2v_o}{c}$: Doppler frequency; $n(t)$: noise

- Target detection: decide between target present ($h \neq 0$) and target absent ($h = 0$) from the radar measurement $r(t)$.
- Estimate target range d_0 .
- Estimate target range rate (velocity) v_0 .

Ambiguity Function

- Correlate the radar return $r(t)$ with the transmit waveform $s(t)$. The correlator output is given by

$$m(\tau - \tau_o, \omega) = \int_{-\infty}^{\infty} h s(t - \tau_o) \overline{s(t - \tau)} e^{-j\omega(t - \tau_o)} dt + \text{noise term}$$

- Without loss of generality, assume $\tau_o = 0$. Then, the receiver output is

$$m(\tau, \omega) = hA(\tau, \omega) + \text{noise term}$$

where

$$A(\tau, \omega) = \int_{-\infty}^{\infty} s(t) \overline{s(t - \tau)} e^{-j\omega t} dt$$

is called the *ambiguity function* of the waveform $s(t)$.

Ambiguity Function

- Ambiguity function $A(\tau, \omega)$ is a two-dimensional function of delay τ and Doppler frequency ω that measures the correlation between a waveform and its Doppler distorted version:

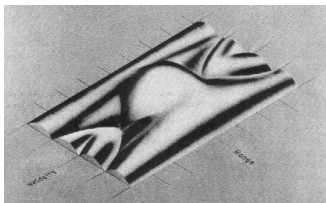
$$A(\tau, \omega) = \int_{-\infty}^{\infty} s(t) \overline{s(t - \tau)} e^{-j\omega t} dt$$

- The ambiguity function along the zero-Doppler axis ($\omega = 0$) is the autocorrelation function of the waveform:

$$A(\tau, 0) = \int_{-\infty}^{\infty} s(t) \overline{s(t - \tau)} dt = R_s(\tau)$$

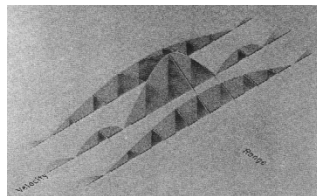
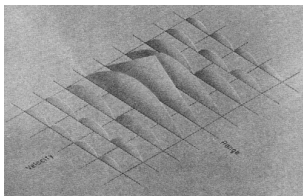
Ambiguity Function

- Example: Ambiguity function of a square pulse



Picture: Skolnik, ch. 11

- Constant velocity (left) and constant range contours (right):



Pictures: Skolnik, ch. 11

Ambiguity Function: Properties

- Symmetry:

$$A(\tau, \omega) = \overline{A(-\tau, -\omega)}$$

- Maximum value:

$$|A(\tau, \omega)| \leq |A(0, 0)| = \int_{-\infty}^{\infty} |s(t)|^2 dt$$

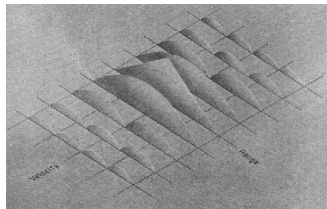
- Volume property (Moyal's Identity):

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |A(\tau, \omega)|^2 d\tau d\omega = |A(0, 0)|^2$$

Pushing $|A(\tau, \omega)|^2$ down in one place makes it pop out somewhere else.

Waveform Design

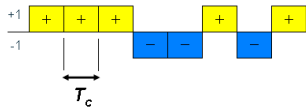
- **Waveform Design Problem:** Design a waveform with a good ambiguity function.
- A point target with delay τ_o and Doppler shift ω_o manifests as the ambiguity function $A(\tau, \omega_o)$ centered at τ_o .
- For multiple point targets we have a superposition of ambiguity functions.
- A weak target located near a strong target can be masked by the sidelobes of the ambiguity function centered around the strong target.



Picture: Skolnik, ch. 11

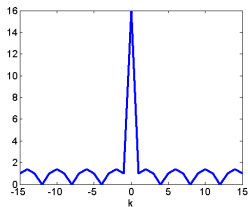
- Phase coded waveform:

$$s(t) = \sum_{\ell=0}^{L-1} x(\ell)u(t - \ell\Delta T)$$

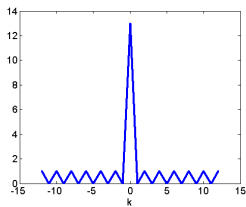


- The pulse shape $u(t)$ and the chip rate ΔT are dictated by the radar hardware.
- $x(\ell)$ is a length- L discrete sequence (or code) that we design.
- Control the waveform ambiguity function by controlling the autocorrelation function of $x(\ell)$.
- Waveform design: Design of discrete sequences with good autocorrelation properties.

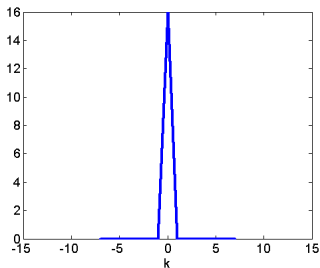
Phase Codes with Good Autocorrelations



Frank Code



Barker Code



Golay Complementary Codes

Waveform Design: Zero Doppler

- Suppose we wish to detect stationary targets in range.
- The ambiguity function along the zero-Doppler axis is the waveform autocorrelation function:

$$\begin{aligned} R_s(\tau) &= \int_{-\infty}^{\infty} s(t) \overline{s(t - \tau)} dt \\ &= \sum_{\ell=0}^{L-1} \sum_{m=0}^{L-1} x(\ell) \overline{x(m)} \int_{-\infty}^{\infty} u(t - \ell\Delta T) \overline{u(t - \tau - m\Delta T)} dt \\ &= \sum_{\ell=0}^{L-1} \sum_{m=0}^{L-1} x(\ell) \overline{x(m)} R_u(\tau + (m - \ell)\Delta T) \\ &= \sum_{k=-2(L-1)}^{2(L-1)} \sum_{\ell=0}^{L-1} x(\ell) \overline{x(\ell - k)} R_u(\tau - k\Delta T) \\ &= \sum_{k=-2(L-1)}^{2(L-1)} C_x(k) R_u(\tau - k\Delta T) \end{aligned}$$

Impulse-like Autocorrelation

- Ideal waveform for resolving targets in range (no range sidelobes):

$$R_s(\tau) = \sum_{k=-2(L-1)}^{2(L-1)} C_x(k) R_u(\tau - k\Delta T) \approx \alpha \delta(\tau)$$

- We do not have control over $R_u(\tau)$.
- **Question:** Can we find the discrete sequence $x(\ell)$ so that $C_x(k)$ is a delta function?
- **Answer:** This is not possible with a single sequence, but we can find a *pair* of sequences $x(\ell)$ and $y(\ell)$ so that

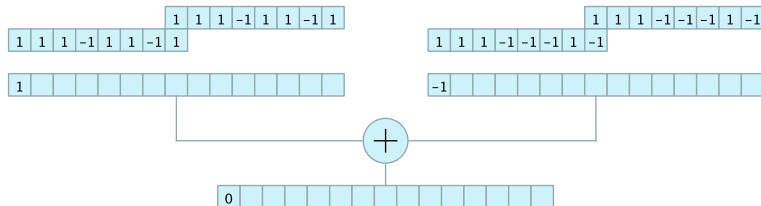
$$C_x(k) + C_y(k) = 2L\delta_{k,0}.$$

Golay Complementary Sequences (Golay Pairs)

Definition: Two length L unimodular sequences $x(\ell)$ and $y(\ell)$ are Golay complementary if the sum of their autocorrelation functions satisfies

$$C_x(k) + C_y(k) = 2L\delta_{k,0}$$

for all $-(L-1) \leq k \leq L-1$.

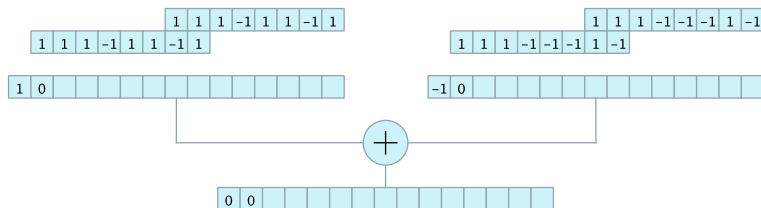


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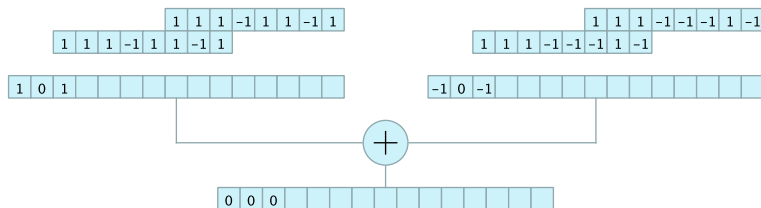


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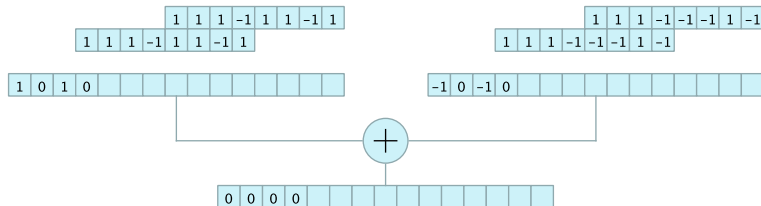


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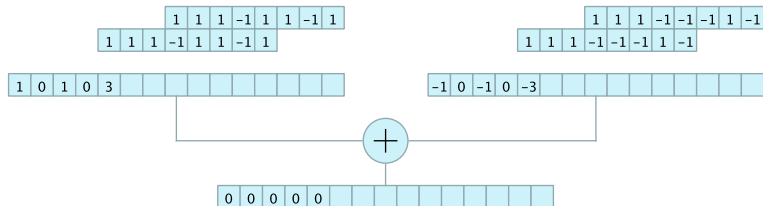


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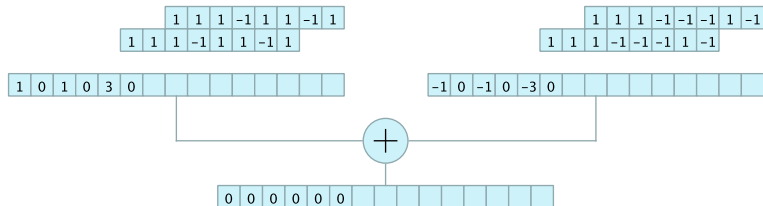


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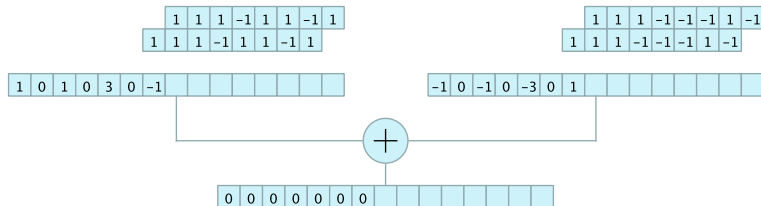


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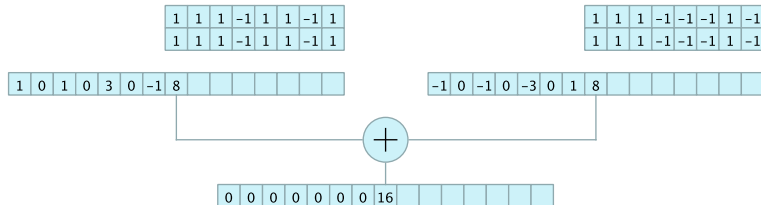


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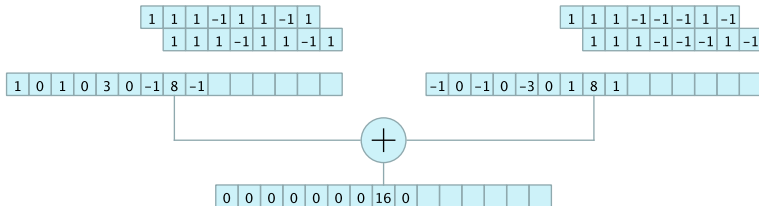


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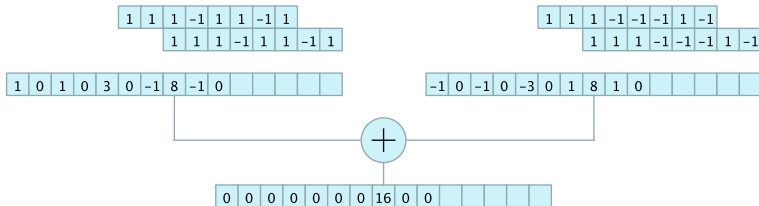


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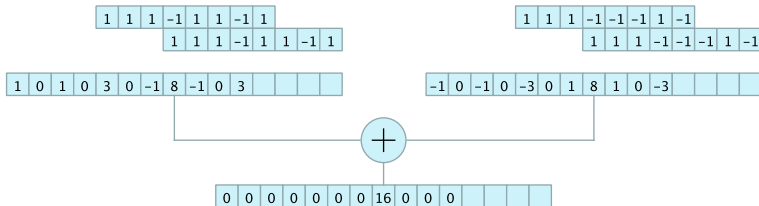


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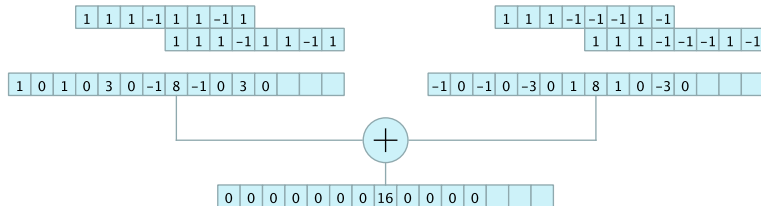


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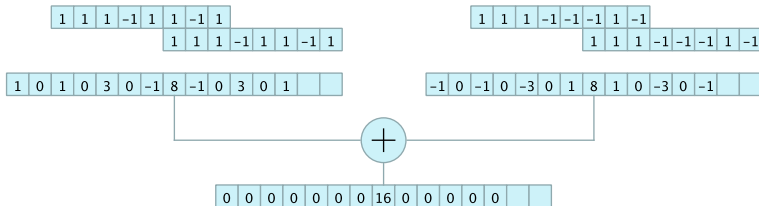


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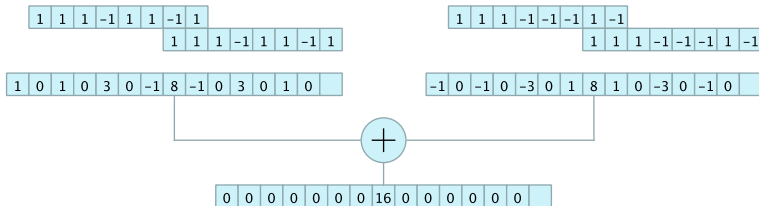


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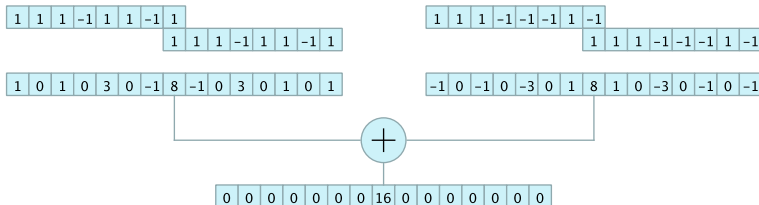


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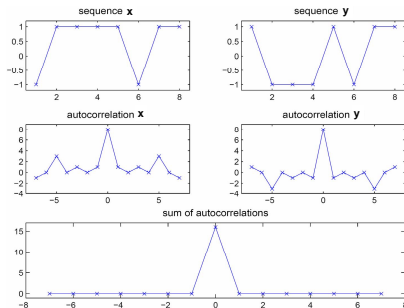
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Golay Pairs: Example



- Time reversal:

$$x: \quad -1 \quad 1 \quad 1 \quad 1 \quad 1 \quad -1 \quad 1 \quad 1$$

$$\tilde{x}: \quad 1 \quad 1 \quad -1 \quad 1 \quad 1 \quad 1 \quad 1 \quad -1$$

- If (x, y) is a Golay pair then $(\pm x, \pm \tilde{y})$, $(\pm \tilde{x}, \pm y)$, and $(\pm \tilde{x}, \pm \tilde{y})$ are also Golay pairs.

Golay Pairs: Construction

- Standard construction: Start with $\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ and apply the construction

$$\begin{pmatrix} A \\ B \end{pmatrix} \longrightarrow \begin{pmatrix} A & B \\ A & -B \\ B & A \\ B & -A \end{pmatrix}$$

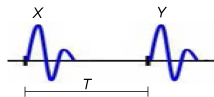
- Example:

$$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 1 & 1 & -1 \\ 1 & 1 & -1 & 1 \\ 1 & -1 & 1 & 1 \\ -1 & 1 & 1 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 1 & 1 & -1 & 1 & 1 & -1 & 1 \\ 1 & 1 & 1 & -1 & -1 & -1 & 1 & -1 \\ 1 & 1 & -1 & 1 & 1 & 1 & 1 & -1 \\ -1 & -1 & 1 & -1 & 1 & 1 & 1 & -1 \\ 1 & -1 & 1 & 1 & -1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 & 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 & 1 & -1 & 1 & 1 \\ 1 & -1 & -1 & -1 & 1 & -1 & 1 & 1 \end{pmatrix}$$

- Other constructions:
 - Weyl-Heisenberg Construction: Howard, Calderbank, and Moran, EURASIP J. ASP 2006
 - Davis and Jedwab: IEEE Trans. IT 1999

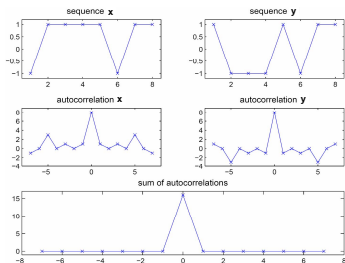
Golay Pairs for Radar: Zero Doppler

- The waveforms coded by Golay pairs x and y are transmitted over two Pulse Repetition Intervals (PRIs) T .

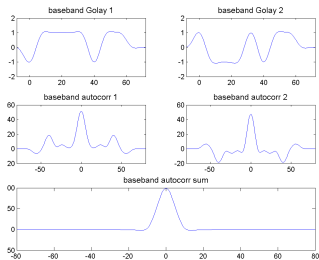


- Each return is correlated with its corresponding sequence:

$$C_x(k) + C_y(k) = 2L\delta_{k,0}$$



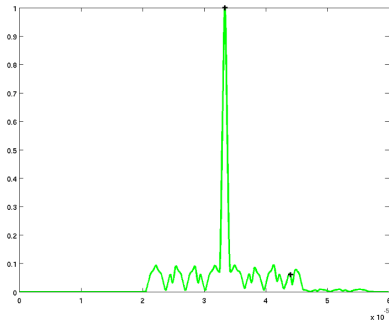
Discrete Sequence



Coded Waveform

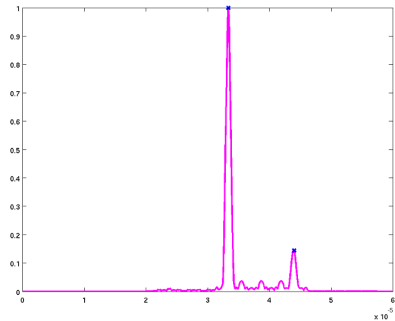
Golay Pairs for Radar: Advantage

Frank coded waveforms



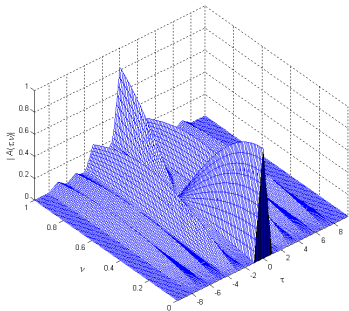
Weaker target is masked

Golay complementary waveforms



Weaker target is resolved

Sensitivity to Doppler

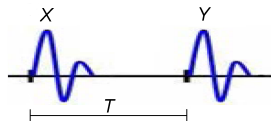


“Although the autocorrelation sidelobe level is zero, the ambiguity function exhibits relatively high sidelobes for nonzero Doppler.” [Levanon, Radar Signals, 2004, p. 264]

$$A_{s_x}(\tau, \nu) + e^{j2\pi\nu T} A_{s_y}(\tau, \nu)$$

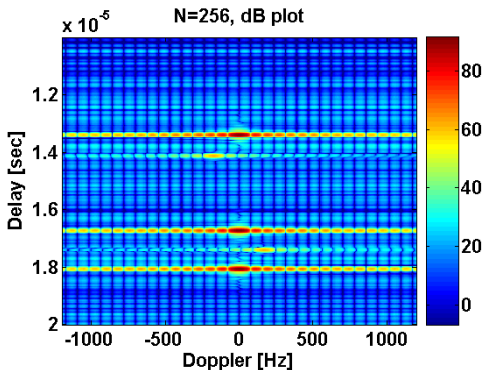
Why? Roughly speaking

$$C_x(k) + C_y(k)e^{j\theta} \neq \alpha(\theta)\delta_{k,0}$$



Sensitivity to Doppler

Range Sidelobes Problem: A weak target located near a strong target can be masked by the range sidelobes of the ambiguity function centered around the strong target.



Range-Doppler image
obtained with conventional
pulse train

x y \dots x y



- 1 M. I. Skolnik, "An introduction and overview of radar," in *Radar Handbook*, M. I. Skolnik, Ed. New York: McGraw-Hill, 2008.
- 2 M. R. Ducoff and B.W. Tietjen, "Pulse compression radar," in *Radar Handbook*, M. I. Skolnik, Ed. New York: McGraw-Hill, 2008.
- 3 S. D. Howard, A. R. Calderbank, and W. Moran, "The finite Heisenberg-Weyl groups in radar and communications," *EURASIP Journal on Applied Signal Processing*, Article ID 85685, 2006.
- 4 N. Levanon and E. Mozeson, *Radar Signals*, New York: Wiley, 2004.
- 5 M. Golay, "Complementary series," *IRE Trans. Inform. Theory*, vol. 7, no. 2, pp. 82-87, April 1961.